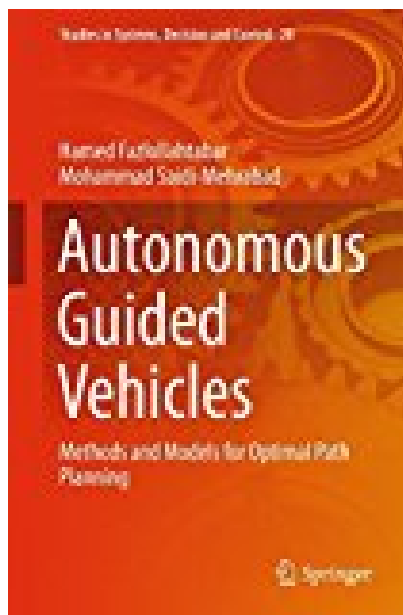


Autonomous Guided Vehicles Methods and Models for Optimal Path Planning Studies in Systems Decision and Control



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